### Multilevel Solvers for Discontinuous Galerkin Methods

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#### Main Objective:

Design and analyze efficient solution techniques for  $\ensuremath{hp}\xspace$  –discontinous Galerkin discretizations of

$$-\nabla \cdot (\mathbf{K} \nabla u) = f \quad \text{ in } \Omega \subset \mathbb{R}^d$$
$$u = 0 \quad \text{ on } \partial \Omega.$$

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Weak formulation of PDE: find  $u_h \in \mathcal{D}_k(\mathcal{E}_h)$  such that

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where the bilinear form  $a_\epsilon$  is given by

$$\begin{split} a_{\epsilon}(u_h, v) &= \sum_{E \in \mathcal{E}_h} \int_E \mathbf{K} \nabla u_h \cdot \nabla v - \sum_{e \in \Gamma_h \cup \Gamma_D} \int_e \{\!\{ \mathbf{K} \nabla u_h \cdot \vec{n}_e \}\!\} [\![v]\!] \\ &+ \epsilon \sum_{e \in \Gamma_h \cup \Gamma_D} \int_e \{\!\{ \mathbf{K} \nabla v \cdot \vec{n}_e \}\!\} [\![u_h]\!] + \sum_{e \in \Gamma_h \cup \Gamma_D} \frac{\sigma_e}{|e|^{\beta_0}} \int_e [\![u_h]\!] [\![v]\!]. \end{split}$$

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To solve this system we employ a Schwarz domain decomposition method:

$$B = \mathbf{R}_0 \mathbf{A}_0^{-1} \mathbf{R}_0^T + \sum_{i=1}^{N_S} \mathbf{R}_i \mathbf{A}_i^{-1} \mathbf{R}_j^T$$

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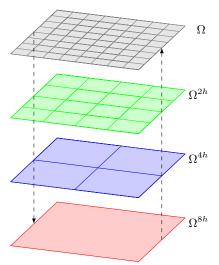
 $R_j$  are elliptic projection operators, and  $\mathbf{A}_j$  are the restriction of  $a_\epsilon(\cdot,\cdot)$  to a subdomain  $\Omega_j$ .

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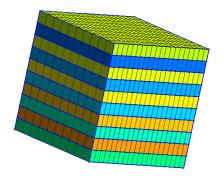
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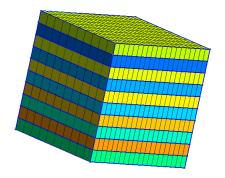
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- The **coarse** grid operator  $(\mathbf{R}_0 \mathbf{A}_0^{-1} \mathbf{R}_0^T)$  is amenable to **coarse** grain parallelism
- The **fine** grid operators  $(\mathbf{R}_j \mathbf{A}_j^{-1} \mathbf{R}_j^T)$  are amenable to **fine** grain parallelism

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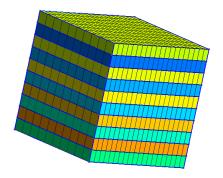


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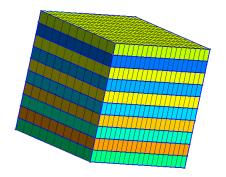
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- Coarse grid is handled by a small number of MPI ranks



# Closer look at mapping to coprocessor

